

Best Paper Award

CVPR 2026 Workshop on World Models Meet Active Sensing and Closed-Loop Planning

This certificate is proudly awarded to

RoboWM-Bench: A Benchmark for Evaluating World Models in Robotic Manipulation

Feng Jiang, Yang Chen, Kyle Xu, Yuchen Liu, Haifeng Wang, Zhenhao Shen, Jasper Lu,
Shengze Huang, Yuanfei Wang, Chen Xie, Ruihai Wu

for their outstanding engagement and valuable contribution to the workshop

Given this **3rd** day of **June**, 2026.

Organized by R. Chellappa, J. Chen, Y. Du, S. Khudanpur, C. Peng, T. Shu, C. Wei, J. Xie, and A. Yuille